

10. Solidification Time in Casting

A cylinder with a diameter-to-height ratio of 1 solidifies in 4 min during a sand-casting operation.

1. What will be the solidification time if the cylinder height is tripled?

From Chvorinov's rule and assuming $n = 2$, we have:

$$t = C \left(\frac{V}{A} \right)^2 = C \left[\frac{\frac{\pi d^2 h}{4}}{\frac{\pi d^2}{2} + \pi d h} \right]^2 = C \left(\frac{dh}{2d + 4h} \right)^2 = 4 \text{ min}$$

Solving for C :

$$C = 4 [\text{min}] \left(\frac{2d + 4h}{dh} \right)^2 = 4 [\text{min}] \left(\frac{\frac{2d}{h} + 4}{d} \right)^2$$

With the ratio $d/h = 1$:

$$C = 144 [\text{min}] \left(\frac{1}{d} \right)^2$$

If the height is tripled, we can use $d_2 = d$ and $h_2 = 3h$ to obtain the solidification time for the new condition as:

$$t = C \left(\frac{d_2 h_2}{2d_2 + 4h_2} \right)^2 = 144 [\text{min}] \left(\frac{1}{d} \right)^2 \left(\frac{3d}{\frac{2d}{h} + 12} \right)^2 \bigg|_{d/h=1}$$

$$t = 144 [\text{min}] \left(\frac{3}{2 + 12} \right)^2 \cong 6.6 \text{ min}$$

2. What will be the solidification time if the cylinder diameter is tripled?

If the diameter is tripled, so that $d_3 = 3d$ and $h_3 = h$, then:

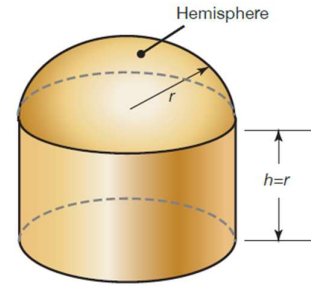
$$t = C \left(\frac{d_3 h_3}{2d_3 + 4h_3} \right)^2 = 144 [\text{min}] \left(\frac{1}{d} \right)^2 \left(\frac{3dh}{2(3d) + 4h} \right)^2 = 144 [\text{min}] \left(\frac{1}{d} \right)^2 \left(\frac{3d}{\frac{6d}{h} + 4} \right)^2 \bigg|_{d/h=1}$$

$$t = 144 [\text{min}] \left(\frac{3}{6 + 4} \right)^2 \cong 13 \text{ min}$$

3. In turns out that the optimum shape of a riser is spherical to ensure that it cools more slowly than the related casting. Spherically shaped risers, however, are difficult to cast.
 - a. Sketch the shape of a blind riser that is easy to mold, but also has the smallest possible surface area-to-volume ratio.
Note. A closed or blind riser is a riser that is contained within the mold. It has no direct contact with the atmosphere.

A sketch of a blind riser that is easy to cast is shown below, consisting of cylindrical and a hemispherical portion.

Note that the height of the cylindrical portion is equal to its radius (so that the total height of the riser is equal to its diameter).



- b. Compare the solidification time of the riser you designed to that of a riser shaped like a simple cylinder. Assume that the volume of each riser is the same ($V = V_s$, where V is the volume of a cylindrical riser with height equal to its radius and V_s the volume your optimized riser).

Hint. Consider an arbitrary unity volume, $V = V_s = 1$ and remember that for both the radius-to-cylinder height ratio is equal to 1.

The volume V_s of this optimized, hemispherical riser is

$$V_s = \pi r^2 h + \frac{1}{2} \left(\frac{4\pi r^3}{3} \right) = \frac{5\pi r^3}{3}$$

Letting V_s be unity, we have

$$r = \left(\frac{3}{5\pi} \right)^{1/3}$$

The surface area of the optimized riser is

$$A_s = 2\pi r h + \pi r^2 + \frac{1}{2} (4\pi r^2) = 5\pi r^2$$

Substituting for r , we find $A_s \cong 5.21$. Therefore, the solidification time for the blind riser will be

$$t_s = B \left(\frac{V_s}{A_s} \right)^2 = B \left(\frac{1}{5.21} \right)^2 \cong 0.037B$$

For a purely cylindrical riser of the same volume, we have

$$V = \pi r'^2 h' = \pi r'^3 \equiv 1$$

$$r' = \left(\frac{1}{\pi} \right)^{1/3}$$

$$A = 2\pi r'^2 + 2\pi r' h' = 2\pi r'^2 + 4\pi r'^2 = 6\pi r'^2 \cong 8.79$$

$$t = B \left(\frac{V}{A} \right)^2 = B \left(\frac{1}{8.79} \right)^2 \cong 0.013B$$

Thus, the optimized blind riser with hemispherical shape will cool three times slower while being easily casted (at least way easier than a fully spherical riser).

11. Turning a Ti-Alloy Rod

A titanium-alloy rod of length $l = 150$ mm and diameter $\phi_i = 75$ mm is being radially reduced to a diameter $\phi_f = 65$ mm by turning on a lathe in one pass. The spindle rotates at $v_s = 400$ rpm and the tool is traveling at an axial velocity of $v_a = 200$ mm/min. Consider that the unit energy required has an average value of $E_{av} = 3.5$ W · s/mm³.

1. Calculate the material removal rate.

The depth of cut can be calculated from the information given as

$$d = \frac{\phi_i - \phi_f}{2} = \frac{75 - 65}{2} = 5 \text{ mm}$$

and the average diameter is $D_{av} = \frac{75+65}{2} = 70$ mm.

Moreover, the feed is

$$f = \frac{v_a}{v_s} = \frac{200}{400} = 0.50 \text{ mm/rev}$$

Therefore, we can compute

$$MRR = \pi D_{av} d f v_s = \pi \cdot 70 \cdot 5 \cdot 0.50 \cdot 400 = 2.2 \cdot 10^5 \text{ mm}^3/\text{min}$$

2. How long does it take for this machining operation to be completed?

The actual time to cut is given by

$$t = \frac{l}{v_a} = \frac{150}{200} = 0.75 \text{ min} = 45 \text{ s}$$

3. What is the required power?

$$P = E_{av} \cdot MRR = \frac{3.5 \cdot 2.2 \cdot 10^5}{60} \cong 13 \text{ kW}$$

4. What is the loading mode in the rod? Characterize and calculate the cutting force F_c .

The material is subjected to pure shear stress, and the cutting force is the tangential force exerted by the tool.

The spindle speed is $v_s = 400 \text{ rpm} \equiv \omega = 41.89 \text{ rad/s}$. Since $P = T \cdot \omega$, we have:

$$T = \frac{P}{\omega} = \frac{13 \cdot 10^3}{41.89} \cong 310 \text{ N} \cdot \text{m}$$

Dividing the torque by the average workpiece radius, we have

$$F_c = \frac{T}{\frac{D_{av}}{2}} = \frac{310}{0.035} \cong 8.9 \text{ kN}$$

12. Tool Wear with Ceramics

Using the Taylor equation for tool wear and choosing the average value out of the possible n values for tools in ceramics, calculate the percentage increase in tool life if the cutting speed is reduced by (a) 30% and (b) 60%.

The Taylor equation for tool wear is an empirical model. It was given in the lecture on Conventional Machining (as well as n for different materials) and can be rewritten for the average case of ceramics as

$$C = V \cdot LT^n = V \cdot LT^{0.6}$$

(where $V = w^x t_0^y v$).

We can compare to cases as

$$V_1 LT_1^n = V_2 LT_2^n \Rightarrow \frac{LT_1}{LT_2} = \left(\frac{V_2}{V_1} \right)^{1/n}$$

(a) For the case where the speed is reduced by 30%, then $V_2 = 0.7V_1$, and thus

$$\frac{LT_1}{LT_2} = \left(\frac{0.7V_1}{V_1} \right)^{1/0.6} \cong 0.55$$

The new life LT_2 is 1.8 times the initial lifetime.

(b) For the case where the speed is reduced by 60%, then $V_2 = 0.4V_1$, and thus

$$\frac{LT_1}{LT_2} = \left(\frac{0.4V_1}{V_1} \right)^{1/0.6} \cong 0.22$$

The new life LT_2 is 4.5 times the initial lifetime.

13. Drilling Holes in a Block of Magnesium

(Adapted from the final exam 2018)

A hole is being drilled in a block of magnesium alloy of thickness $t_b = 2$ cm, with a $\phi_d = 15$ mm drill in high-speed steel ($\sigma_{y,HSS} = 1000$ MPa, $E_{HSS} = 200$ GPa, $\nu_{HSS} = 0.29$) at a feed of $f = 0.20$ mm/rev. The spindle is running at $v_s = 500$ rpm.

Consider that the unit energy required has an average value of $E_{av} = 0.5$ W · s/mm³.

1. Express the MRR for a drill bit of diameter ϕ_d , a feed rate f and spindle rotational speed v_s .

The MRR can be calculated logically from the volume of matter removed per turn and at a certain rate:

$$MRR = \frac{\pi \phi_d^2}{4} f v_s$$

2. Calculate the MRR , and estimate the torque on the drill.

$$MRR = \frac{\pi 15^3}{4} \cdot 0.20 \cdot 500 \cong 1.8 \cdot 10^4 \text{ mm}^3/\text{min} \cong 300 \text{ mm}^3/\text{s}$$

Using the average specific energy for magnesium alloys, we find:

$$P = E_{av} \cdot MRR = 0.5 \cdot 300 = 150 \text{ W}$$

The power is the product of the torque on the drill and the rotation speed in radians per second, which, in this case is:

$$\omega = \frac{2\pi v_s}{60} = \frac{2\pi \cdot 500}{60} \cong 52.4 \text{ rad/s}$$

Which gives for the torque:

$$T = \frac{P}{\omega} = \frac{150}{52.4} \cong 2.86 \text{ N} \cdot \text{m}$$

3. Express and compute the angle of twist ϕ seen by the drill during the process as a function of the given parameters.

The maximum shear strain on the drill is $\gamma = \frac{\phi_d \phi}{L}$ where ϕ is the angle of twist and $L \geq t_b$ is the drill length.

The maximum shear stress on the drill is $\tau = \frac{\phi_d T}{J}$ where $J = \frac{\pi}{2} \left(\frac{\phi_d}{2}\right)^4$ is the second moment of area of the drill (assuming that the drill is a solid rod).

Now we can use Hooke's law in shear for the angle of twist:

$$\tau = G\gamma = G \frac{\phi_d \phi}{L} = \frac{\phi_d T}{J} \Rightarrow \phi = \frac{TL}{GJ} = \frac{64(1+\nu) TL}{\pi E} \left(\frac{1}{\phi_d}\right)^4$$

Numerical application:

$$\phi = \frac{64(1+0.29)}{\pi} \frac{2.86 \cdot 2 \cdot 10^{-2}}{200 \cdot 10^9} \left(\frac{1}{15 \cdot 10^{-3}}\right)^4 \cong 1.48 \cdot 10^{-4} \text{ rad} \cong 0.00850^\circ$$